WHITE PAPER



OBJECT-BASED VECTORIZATION OF GEOSPATIAL DATA – AN AI APPROACH

Abstract

Vectorization—the process of converting raster data into vector format—remains a significant challenge in the geospatial industry. Traditional methods of producing a vector data from a raster, especially when working with scanned PDFs, make image interpretation complex and require substantial manual effort to accurately map the individual assets. This white paper presents a proof of concept that leverages an Al-driven approach to automate this conversion process by handling the map data as layered components or objects, such as electrical conductors, roads, and buildings. The focus is on extracting line and polygon features using BOTs, which substantially reduces manual effort and enhances efficiency.





Business Challenge

The mapping of utilities, assets, and topography using digital technology is key to effective management and better use of spatial data. New tools and innovative approaches are required for utility providers to stay competitive. In this context, converting raster files to vector format—also known as vectorization plays a crucial role in processing and managing geospatial data with efficiency and accuracy. However, this vectorization process is traditionally complex and labor-intensive as it involves interpreting the image characteristics, such as lines and polygons, and mapping individual assets manually. The primary challenge lies in finding a concrete, reliable method to effectively convert scanned images into vector representation (i.e. points, line, and areas).

Traditional approaches to interpreting data from the raster images, such as scanned

PDFs, hinders and complicates automation efforts. From a legacy modernization perspective, finding an effective conversion process is crucial to minimize operational costs while maximizing accuracy. This white paper proposes a novel method of handling data as individual layers or objects, each with its own characteristic features, allowing for more precise and efficient process of data conversion from raster to vector format.



Approach

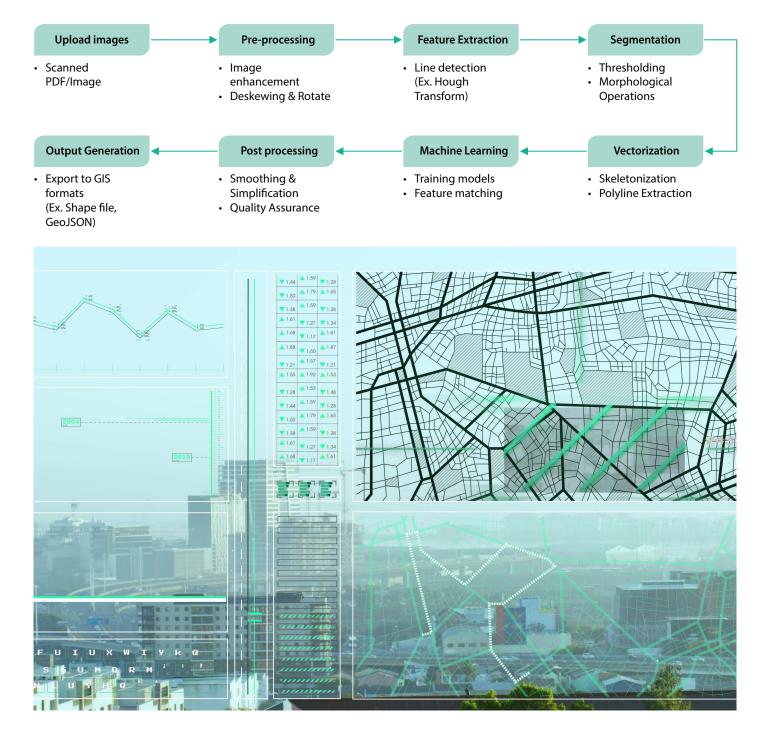
This Al-driven PoC approach focuses on extracting and converting the linear and polygonal features into structured layers through a workflow discussed below.

Experimentation with high-level workflow

The high-level workflow depicts the various stages of vectorization process. This workflow has been adopted to derive

the automated output and cleanse the deliverables using commercial off-the-shelf (COTs) data reviewing and cleansing tools. The stages of vectorization process are illustrated in the figure below.

High-level workflow



Source of PoC Data

Scanned PDFs from electric utilities were used as the primary data source for this white paper. These scanned PDFs contain utility facilities or network components, such as electrical conductors and road network presented as linear features. The scanned images also identify other land base, polygonal features such as buildings.

Pre-processing

In this stage, the quality of the scanned image is enhanced using techniques such as contrast adjustment, noise reduction, and binarization. This stage involves deskewing and rotation where any skewness or rotation in the image is automatically corrected to ensure that the features are properly aligned.

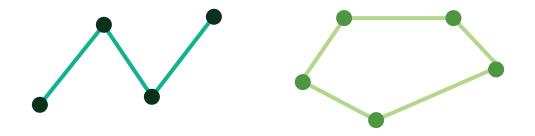
Feature Extraction

This stage focuses on mapping linear features such as electrical conductors and roads with enhanced accuracy. It includes several key processing steps to ensure precise extraction and representation of these line features.

Segmentation

This stage involves *thresholding* where the image is converted into a binary format, effectively distinguishing linear features

from the background. This stage also involves *morphological operations*, utilizing techniques, such as dilation and erosion, to refine the extracted features, thereby improving accuracy and clarity.

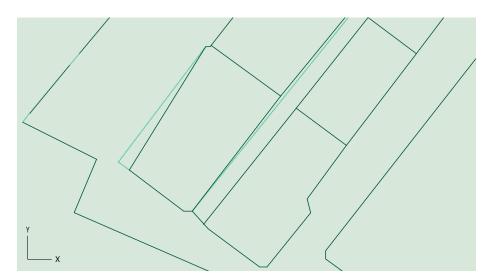


Vectorization

This process involves extracting or identifying lines and polygons from the scanned images. When scanned lines appear several pixels wide, the first step is typically to thin them down to retain only their centerline or skeleton. This process, known as **skeletonization**, reduces the thickness of the lines to a single pixel width, creating a simplified, skeletal representation of the original features.

Next is **polyline extraction**, which involves tracing the skeletal lines and curves to

transform them into vector data. In this step, the thin skeletal lines are converted into a series of coordinate pairs or points that define a polyline, enriching them with meaningful data for further analysis or use.



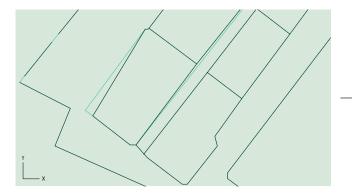
Machine Learning

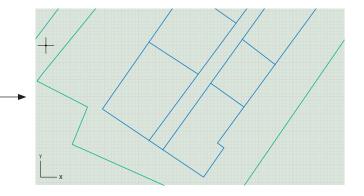
Machine learning plays a crucial role in automating feature extraction, particularly in recognizing and classifying linear features. Training models, such as *Convolutional Neural Networks* (CNNs), enable accurate identification of different types of linear elements. These trained models are then utilized for feature matching, allowing extracted elements to be categorized into predefined classes, such as roads and electrical conductors.



Post Processing

Post-processing steps further refine the results, including smoothening and simplification techniques to reduce the number of vertices while preserving essential details. Additionally, quality assurance measures, whether manual or automated, are employed to validate and correct any errors in the vectorized data, ensuring high accuracy and reliability.





Output Generation

The final step in the process involves exporting the vectorized data into standard GIS formats for further analysis and practical applications. Converting the processed data into widely used formats such as *Shapefiles* or *GeoJSON* ensures compatibility with various GIS platforms, enabling seamless integration into mapping, spatial analysis, and infrastructure planning workflows. This structured output allows for efficient data sharing, visualization, and advanced geospatial analysis, supporting diverse use cases in urban planning, utility management, and transportation networks.

The automated output is cleaned using data reviewing and cleansing tool. For this case, the CAD tools were utilized.

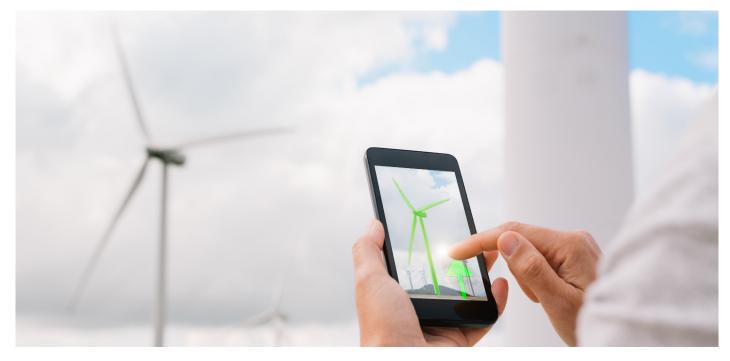


Analyzing the Results

This proof of concept demonstrated significant effort savings across different feature types and complexities. The metrics are summarized below:

	Weighted Overlay	Unit – Minutes			Savings in TAT
Feature Type	Density	Manual Effort	Semi-Automatic Effort	Savings	
Line (Electrical conductors and roads)	Medium	105	40	65	62%
	Complex	390	210	180	46%
Polygon (Buildings)	Medium	15	5	10	67%
	Complex	45	15	30	67%

These metrics indicate substantial effort savings based on the proposed object-based geometric handling methods.



Technical Development

To ensure the best deliverables, it is crucial to develop specific Al-powered tools tailored to the project's requirements. The following proposed tools aim to enhance the efficiency and accuracy of mapping geospatial features.

Line Geometry Tool

This tool will focus on mapping linear features, such as electrical conductors and roads. It automates the detection and mapping of lines from raster data, significantly reducing the need for manual intervention.

The tool will focus on mapping polygonal features, especially buildings. Its primary functionality is to identify and outline building shapes from raster images with high precision. This ensures accurate mapping while enhancing efficiency. By leveraging this tool, users can achieve improved accuracy in capturing building footprints, significantly reducing turnaround times and minimizing manual effort.

Shape Geometry Tool



Budget Considerations

The development of these AI-based tools is anticipated to require a modest budget, but initial studies and previous experience suggest they could potentially lead to substantial cost savings.

These savings will be achieved through several key factors. First, reduced manual

Key Takeaways

This proof of concept highlights the feasibility and efficiency of automating raster image to vector conversion using a layered (object-based) approach. By focusing on individual geometrical objects and leveraging tools such as BOTs, effort will be made possible by automation, significantly cutting down the time and resources spent on manual mapping tasks. Second, increased efficiency will be driven by Al-powered tools that speed up the mapping process, allowing for quicker project completion. Finally, enhanced accuracy in mapping will minimize errors, reducing the need for costly corrections and rework. Overall, these improvements will optimize workflow, reduce costs, and enhance overall project productivity.

significant reductions in manual effort were achieved. Additionally, this method is scalable, making it suitable for large-scale applications across various geospatial domains, including mapping, infrastructure monitoring, utility management, and more. Al-driven automation enhances efficiency, driving broader adoption in industries that depend on accurate and timely geospatial data processing.



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